

# DRAW WIRE SENSOR



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# Series SX135

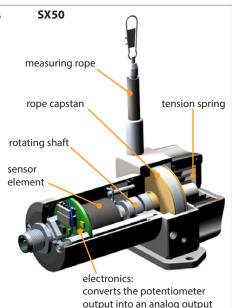
# **Key-Features:**

- Measurement ranges from 10.0 to 42.5 m
- Analog Output: Potentiometer, 0...10 V, 4...20 mA
- teachable outputs: 0...5 V, 0...10 V, with an additional Open-Collector switching output
- Incremental Output: RS422 (TTL), push-pull (HTL)
- Digital Output Absolute: CANopen, SSI, Profibus, EtherCAT, Profinet
- Linearity up to ±0.02% of full scale
- Protection class up to IP67
- Temperature range -20...+85 °C (optional -40 °C)
- High dynamics
- High interference immunity factor
- Customised versions available

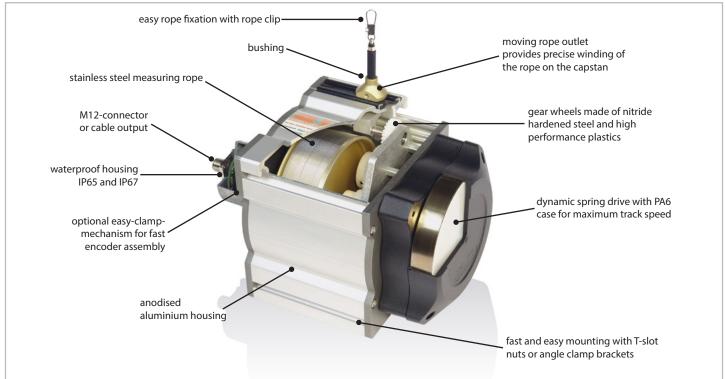
WayCon Positionsmesstechnik GmbH is a manufacturer of high quality draw wire position sensors for industrial use. Due to its small overall size, its short assembly time and its possible customisation, the SX sensor technology is a cost-effective and flexible solution for a wide range of industrial applications. The dynamics of the draw wire transducer allows a high motion speed and acceleration of the measuring target. Its rugged design and high quality makes applications in harsh industrial environments possible. Special instruments are available with mounting service of encoder on site, as well as customised versions of housing.

#### Sensor principle:

The key component of a draw wire sensor is a highly flexible steel wire rope, that is winded single-layered on an ultra-light capstan. This capstan is connected to the sensor housing by a prestressed spring. The end of the steel wire rope, that is equipped with a rope clip gets connected to the target object. As soon as the distance between sensor and target object changes, the steel wire rope gets pulled out of the sensor and is rolled off the capstan (or vice versa). The shaft of the capstan is connected to a potentiometer (for analog output signals), or to an encoder (for digital output signals). If there is a rotation of the capstan due to a change in the distance to the target object, the sensor element will turn proportionally. This way the potentiometer, or the encoder converts a linear movement into a proportional electrical signal. If a standard analog output signal, like 0...10 V or 4...20 mA is needed, the sensor is equipped with additional electronics.



#### **OVERVIEW OF FEATURES**



#### **WARNING NOTICES**

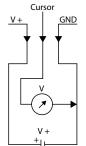
- Don't let the rope snap back. If the rope is retracted freely, this may lead to injuries (whiplash effect) and the device may be damaged. Caution when unhooking and retracting the rope into the sensor.
- Never exceed the specified measurement range when extracting the rope!
- Do not try to open the device. The stored energy of the spring drive may lead to injuries when being mishandled.
- Do not touch the rope when operating the sensor.
- Avoid guiding the rope over edges or corners. Use a deflection pulley instead.
- Do not operate the sensor if the rope is buckled or damaged. A ripping of the rope may lead to injuries or a damaging of the sensor.

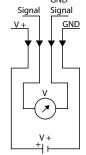
| Measurement range * | [m] | 10 | 12  | 15 | 20  | 25           | 30   | 35 | 40 | 42.5 |
|---------------------|-----|----|---|----|-----|--------------|------|----|----|------|
| Linearity           | [%] |    |   |    |     | ±0.1         |      |    |    |      |
| Resolution          |     |    | see output types below  |    |     |              |      |    |    |      |
| Sensor element      |     |    | Hybrid Potentiometer  |    |     |              |      |    |    |      |
| Connection          |     |    | connector output M12 or cable output axial (TPE cable, standard length 2 m)       |    |     |              |      |    |    |      |
| Protection class    |     |    |   |    | IPe | 55, optional | IP67 |    |    |      |
| Humidity            |     |    | maximum 90 % relative, no condensation  |    |     |              |      |    |    |      |
| Temperature         |     |    | see output types below  |    |     |              |      |    |    |      |
| Mechanical data     |     |    | extraction force, maximum velocity and maximum acceleration see "Mechanical Data" |    |     |              |      |    |    |      |
| Weight              | [g] |    | 3200 to 5000, depending on the measurement range                                  |    |     |              |      |    |    |      |
| Housing             |     |    | aluminium, anodised, spring case PA6  |    |     |              |      |    |    |      |

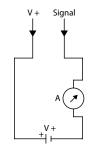
<sup>\*</sup> other ranges on request

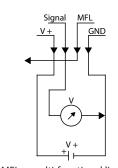
# **ELECTRICAL DATA ANALOG OUTPUT**

|                                     | Potentiometer 1 kΩ                               | Voltage 05 V, 010 V                                  | Current 420 mA                     | Voltage 05 V, 010 V<br>(teachable up to 50 % MR)     |
|-------------------------------------|--|--|------------------------------------|--|
| Output                              | 1 kΩ   | 05 V, 010 V, galvanically isolated, 4 conductors     | 420 mA, 2 conductors               | 05 V, 010 V, 3 conductors                            |
| Power supply                        | max. 30 V  | 123  | 0 VDC                              | 835 VDC  |
| Recommended cursor current          | < 1 μΑ   |  | -                                  |  |
| Current consumption max.            | -  | 22.5 mA (unloaded)                                   |                                    |  |
| Current consumption max.            | -  | -  | -                                  | 150 mW   |
| Output current                      | -  | max. 10 mA, min. load 10 kΩ                          | max. 50 mA in case of error        | max. 10 mA, min. load 1 k $\Omega$                   |
| Dynamics                            | -  | < 3 ms from 0100 % and 1000 %                        | < 1 ms from 0100 % and 1000 %      | 1 ms   |
| Resolution                          | theor  | etically unlimited, limited by the                   | noise                              | 1 mV   |
| Noise                               | dependent on the quality of the power supply     | 3 mV <sub>pp</sub> typical, max. 37 mV <sub>pp</sub> | 0.03 mApp = 6 mVpp at 200 $\Omega$ | 3 mV <sub>pp</sub> typical, max. 37 mV <sub>pp</sub> |
| Inverse-polarity protection         | -  |  | yes, infinite                      |  |
| Short-circuit proof                 | -  | yes, permanent                                       | -                                  | yes, permanent                                       |
| Working temperature                 | -20+85 °C / optional:<br>-40+85 °C or -20+120 °C | -  | .20+85 °C / optional: -40+85 °C    |  |
| Temperature coefficient             | ± 0.0025 %/K                                     | 0.0037 %/K   | 0.0079 %/K                         | 0.0016 %/K   |
| Elektromagnetic compatibility (EMC) | -  |  | according to EN 61326-1:2013       |  |
| Circuit                             | Cursor<br>V+ GND                                 | GND<br>Signal Signal<br>V + GND                      | V + Signal                         | Signal MFL<br>V + GND                                |









MFL = multi-functional line

# TECHNICAL DATA DIGITAL OUTPUT INCREMENTAL

| Measurement range *           | [m]         | 10  | 12  | 15              | 20            | 25            | 30            | 35           | 40           | 42.5       |
|-------------------------------|-------------|---|---|-----------------|---------------|---------------|---------------|--------------|--------------|------------|
| Linearity                     | [%]         |   |   | ±0.05           | (independe    | ent of the me | asurement ra  | ange)        |              |            |
| Improved linearity (optional) | [%]         | ±0.02 (ind  | ependent of   | the measure     | ment range,   | only in com   | bination with | resolution 6 | 5 pulses/mm, | or higher) |
| Selectable resolution         | [Pulses/mm] | 0   | .3/3/6/15   | (the resolution | on can be rai | sed by the fa | ctor 4 using  | quadruple e  | dge detectio | n)         |
| Z-Pulse distance              | [mm]        |   |   |                 |               | 333.33        |               |              |              |            |
| Sensor element                |             |   | Incremental-Encoder with optical code disk                                    |                 |               |               |               |              |              |            |
| Output signal                 |             |   | A, B and Z pulse (plus inverted pulses /A, /B and /Z)                         |                 |               |               |               |              |              |            |
| Connection                    |             |   | connector output M12 or M23 or radial cable output (PVC, standard length 2 m) |                 |               |               |               |              |              |            |
| Protection class              |             |   | IP65, optional IP67   |                 |               |               |               |              |              |            |
| Humidity                      |             |   | maximum 90 % relative, no condensation  |                 |               |               |               |              |              |            |
| Temperature range             | [°C]        |   | -20+85  |                 |               |               |               |              |              |            |
| Mechanical data               |             | extraction force, maximum velocity and maximum acceleration see "Mechanical Data" |   |                 |               |               |               |              |              |            |
| Weight                        | [g]         |   |   | 3200 to         | 5000, deper   | nding on the  | measuremen    | nt range     |              |            |
| Housing                       |             |   |   |                 | aluminium,    | anodised, sp  | ring case PA6 | i            |              |            |

<sup>\*</sup> others on request

# **ELECTRICAL DATA DIGITAL OUTPUT INCREMENTAL**

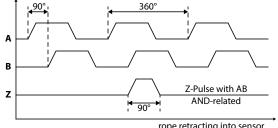
|                               |       | Line drive<br>RS422 (TTL-com |                            |             | Pull G<br>HTL)                           |  |
|-------------------------------|-------|------------------------------|----------------------------|-------------|--|--|
| Power supply                  | [VDC] | 5, ±5 %                      |                            | 8.          | 30                                       |  |
| Current consumption (no load) | [mA]  | typical 40, ma               | ax. 90                     | typical 4   | 0, max. 100                              |  |
| Load / Channel                | [mA]  | max. ±20                     | )                          | max. ±40    |  |  |
| Pulse frequency               | [kHz] | max. 300                     | )                          | ma          | x. 200                                   |  |
| Signal level high             | [V]   | min. 2.5                     |                            | min         | .V+ - 3                                  |  |
| Signal level low              | [V]   |                              | max                        | c. 0.5      |  |  |
| Recommended circuit           |       | Sensor<br>+5 V<br>A          | Circuit +5 V 0 V Z = 120 Ω | Sensor A /A | Circuit $V + = 830 V$ $R_{L} = 1 \Omega$ |  |

# **OUTPUT SIGNAL DIGITAL OUTPUT INCREMENTAL**

#### **Output signal**

Pulses A and B are 90° phase-delayed (detection of direction). The Z-Pulse is emitted once per turn. The Z-Pulse distance is 333.33 mm (= circumference of the rope drum) and can be used as a reference mark.

(The diagram shows the signal without inverted signals; time line for return of rope.)



rope retracting into sensor

# **ELECTRICAL DATA DIGITAL OUTPUT ABSOLUTE CANopen (WCAN)**

| CAN specification                   |       | Full CAN 2.0B (ISO11898)  |
|-------------------------------------|-------|---|
| Communication profile               |       | CANopen CiA 301 V 4.2.0   |
| Device profile                      |       | Encoder, absolute linear; CIA 406 V 3.2.0   |
| Error control                       |       | Producer Heartbeat, Emergency Message, Node Guarding  |
| Node ID                             |       | Default: 7, configurable via SDO and Squeezer (offline configuration) *                             |
| PDO                                 |       | 1 x TPDO, static mapping  |
| PDO Modes                           |       | Event-triggered, Time-triggered, Sync-cyclic, Sync-acyclic  |
| Transmission rate                   |       | 1 Mbps, 800, 500, 250, 125, 50, 20 kbps configurable via SDO and Squeezer (offline configuration) * |
| Bus connection                      |       | M12 connector, 5 pins   |
| Integrated Bus termination resistor |       | 120 $\Omega$ , connectible via SDO and Squeezer (offline configuration) *                           |
| Bus, galvanic separation            |       | No  |
| Power supply                        | [VDC] | 830   |
| Current consumption                 |       | 10 mA typical at 24 V, 20 mA typical at 12 V  |
| Measurement rate                    |       | 1 kHz with 16-bit resolution  |
| Repeatability                       | [%]   | ±0.15 or ±0.1 (according to the selected linearity)   |
| Electrical protection               |       | inverse polarity protection   |
| Working temperature                 | [°C]  | Standard: -20+85 / optional: -40+85   |
| Temperature coefficient             | [%/K] | 0.0014  |
| EMV                                 |       | DIN EN61326-1:2013, conformity with directive 2014/30/EU  |
|                                     |       |   |

<sup>\*</sup> Offline configuration via Squeezer only in combination with M12 connector 8 pins. For more information on the offline configuration please refer to the CANopen <u>manual</u>. For dimensions see technical drawing of analog output on page 9.

# TECHNICAL DATA DIGITAL OUTPUT ABSOLUTE

|  |                      | SSI   | CANopen                                      | Profibus-DP             | EtherCAT         | Profinet |  |
|--|----------------------|---|--|-------------------------|------------------|----------|--|
| Measurement range                        | [m]                  | 10 / 12 / 15 / 20 / 25 / 30 / 35 / 40 / 42.5                                      |  |                         |                  |          |  |
| Linearity                                | [%]                  |   | ±0.05 (independent of the measurement range) |                         |                  |          |  |
| Resolution scalable (with Software)      |                      | no yes  |  |                         |                  |          |  |
| Standard resolution                      | [Pulses/mm]<br>[Bit] | 24.58<br>12 24.58   |  |                         |                  |          |  |
| Maximum resolution                       | [Pulses/mm]<br>[Bit] | - 196.61<br>- 16  |  |                         |                  |          |  |
| Sensor element                           |                      | Multiturn-Absolute-Encoder with optical code disk                                 |  |                         |                  |          |  |
| Connection                               |                      | see order code  |  |                         |                  |          |  |
| Power supply                             | [VDC]                |   | 1030 (reverse po                             | olarity protection of t | he power supply) |          |  |
| Current consumption (no load, at 24 VDC) | [mA]                 | max. 50   | max. 100                                     | max.                    | 120              | max. 200 |  |
| Protection class                         |                      |   |  | IP65, optional IP67     |                  |          |  |
| Humidity                                 |                      |   | max. 90                                      | % relative, no conde    | nsation          |          |  |
| Temperature                              | [°C]                 | -20+80  |  |                         |                  |          |  |
| Mechanical data                          |                      | extraction force, maximum velocity and maximum acceleration see "Mechanical Data" |  |                         |                  |          |  |
| Weight                                   | [g]                  | 3200 to 5000, depending on the measurement range                                  |  |                         |                  |          |  |
| Housing                                  |                      | aluminium, anodised, spring case PA6  |  |                         |                  |          |  |
| Special cables needed                    |                      |   |  | yes                     |                  |          |  |

# **ELECTRICAL DATA DIGITAL OUTPUT ABSOLUTE**

| Parameters of the SSI interface |  |  |  |  |
|---------------------------------|--|--|--|--|
| Code                            | Gray   |  |  |  |
| Output driver                   | RS485 Transceiver-Typ  |  |  |  |
| Permissible load / channel      | max. ±20 mA  |  |  |  |
| Signal level                    | HIGH: typ 3.8 V<br>LOW: with I <sub>Last</sub> = 20 mA typ 1.3 V |  |  |  |
| Resolution                      | 12 bit   |  |  |  |
| SSI clock rate                  | ST-resolution: 50 kHz2 MHz                                       |  |  |  |
| Monoflop time                   | ≤ 15 μs  |  |  |  |
| Data refresh rate               | ≤ 1 µs   |  |  |  |
| Status and Parity bit           | on request   |  |  |  |

| Parameters of the Profibus DP interface |  |  |  |  |
|---|--|--|--|--|
| Code                                    | Binary   |  |  |  |
| Interface                               | Profibus DP 2.0 Standard (DIN 19245 Part 3),<br>RS485 Driver galvanically isolated |  |  |  |
| Protocol                                | Profibus Encoder Profile V1.1 Class1 and Class2 with manufacturer-specific add-ons |  |  |  |
| Baud rate                               | maximum 12 Mbit/s  |  |  |  |
| Device address                          | 1127 (set by rotary switches)  |  |  |  |
| Termination switchable                  | set by DIP switches  |  |  |  |
| SET Button (Option)                     | Zero or defined value option   |  |  |  |
| LED                                     | LED is ON with the following fault conditions:<br>Sensor error, Profibus error     |  |  |  |

| Parameters of the Profinet interface                              |   |  |  |  |  |  |
|---|---|--|--|--|--|--|
| Code  | Binary  |  |  |  |  |  |
| Protocol  | PROFINET 10   |  |  |  |  |  |
| LED Link1/Link2   | green = active link / yellow = data transfer  |  |  |  |  |  |
| Ezturn Software<br>for Profinet<br>(supplied with the<br>encoder) | <ul> <li>Monitoring of cyclic data (e.g. position, speed)</li> <li>Monitoring of acyclic data (e.g. IMO, electronic name plate, encoder parameters, warnings and error messages, preset)</li> <li>Setting of preset values</li> <li>Firmware updates via the bus</li> </ul> |  |  |  |  |  |

| Parameters of the CANopen interface (CAN) |  |  |  |  |
|---|--|--|--|--|
| Code                                      | Binary   |  |  |  |
| Interface                                 | CAN High-Speed acc. to ISO 11898, Basic- and Full-<br>CAN, CAN Specification 2.0 B   |  |  |  |
| Protocol                                  | CANopen profile DS406 V3.2 with manufacturer-<br>specific add-ons  |  |  |  |
| Baud rate                                 | 10 1000 kbit/s (can be set via DIP switches/<br>Software configurable)   |  |  |  |
| Node address                              | 1127 (can be set via rotary switches/ Software configurable)   |  |  |  |
| Termination                               | can be set via DIP switches/ Software configurable   |  |  |  |
| SET Butten (Option)                       | Zero or defined value option   |  |  |  |
| LED                                       | LED is ON with the following fault conditions:<br>Sensor error (internal code or LED error) too low<br>voltage, over-temperature |  |  |  |

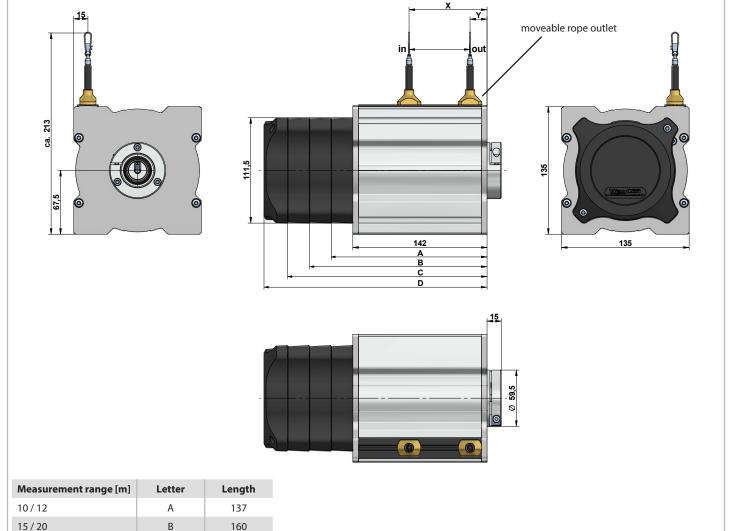
| Parameters of the EtherCAT interface |   |  |  |  |  |
|--------------------------------------|---|--|--|--|--|
| Code                                 | Binary  |  |  |  |  |
| Protocol                             | EtherNet / EtherCAT   |  |  |  |  |
| Modes                                | Freerun, Distributed Clock  |  |  |  |  |
| Diagnostic LED red                   | LED is ON with the following fault conditions: Sensor error (internal code or LED error), low voltage, over-temperature |  |  |  |  |
| Run LED green                        | LED is ON with the following conditions: Preop-,<br>Safeop and Op-State (EtherCAT Status machine)                       |  |  |  |  |
| 2 x Link LEDs<br>yellow              | LED is ON with the following conditions (Port IN and Port OUT): Link detected   |  |  |  |  |

# MECHANICAL DATA

| Measurement range [m] | Extraction force F <sub>min</sub> [N] | Extraction force F <sub>max</sub> [N] | Velocity V <sub>max</sub> [m/s] * | Acceleration a <sub>max</sub> [m/s <sup>2</sup> ] * |
|-----------------------|---------------------------------------|---------------------------------------|-----------------------------------|---|
| 10                    | 4.8                                   | 7.2                                   | 6                                 | 80  |
| 12                    | 4.8                                   | 7.2                                   | 6                                 | 80  |
| 15                    | 6.8                                   | 11.2                                  | 6                                 | 80  |
| 20                    | 6.4                                   | 9.2                                   | 5                                 | 60  |
| 25                    | 7.8                                   | 11.4                                  | 5                                 | 60  |
| 30                    | 6.4                                   | 9.6                                   | 5                                 | 60  |
| 35                    | 7.4                                   | 11.6                                  | 5                                 | 60  |
| 40                    | 5.4                                   | 9                                     | 5                                 | 60  |
| 42.5                  | 5.4                                   | 9                                     | 5                                 | 60  |

<sup>\*</sup> mit Option IP67 auf 60 % reduziert

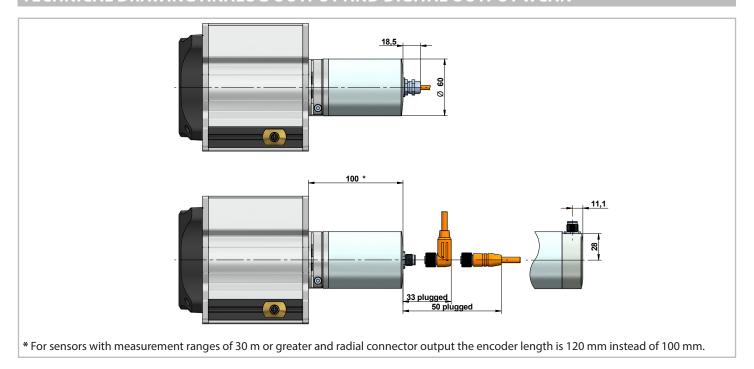
# **TECHNICAL DRAWING**



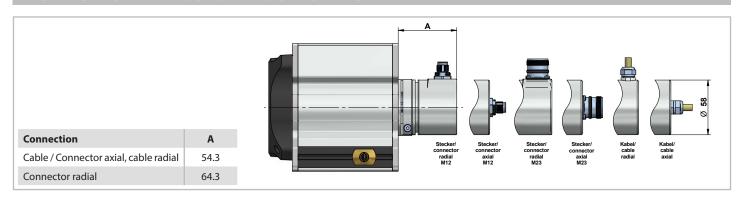
| Measurement range [m] | Letter | Length |
|-----------------------|--------|--------|
| 10 / 12               | А      | 137    |
| 15 / 20               | В      | 160    |
| 25 / 30               | С      | 213    |
| 35 / 40 / 42.5        | D      | 236    |

| Position rope outlet at        | 10 m | 12 m | 15 m | 20 m | 25 m | 30 m | 35 m | 40 m | 42.5 m |
|--------------------------------|------|------|------|------|------|------|------|------|--------|
| start of measurement range (X) | 33   | 36   | 41   | 48   | 56   | 63   | 71   | 78   | 82     |
| end of measurement range (Y)   | 18   | 18   | 18   | 18   | 18   | 18   | 18   | 18   | 18     |

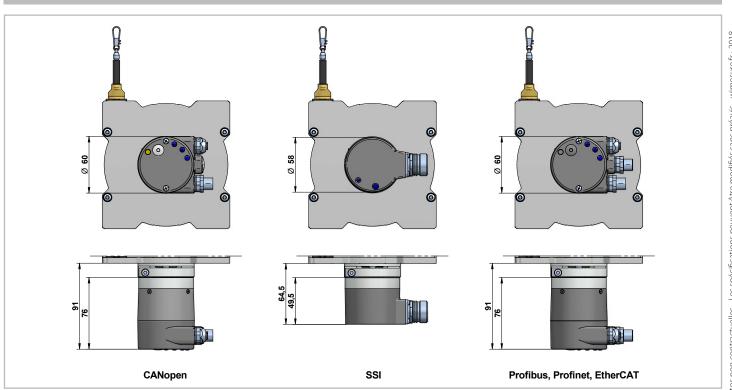
# TECHNICAL DRAWING ANALOG OUTPUT AND DIGITAL OUTPUT WCAN



# **TECHNICAL DRAWING DIGITAL OUTPUT INCREMENTAL**



#### **TECHNICAL DRAWING DIGITAL OUTPUT ABSOLUTE**

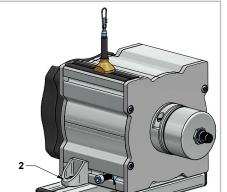


#### 1. by using the grooves in the sensor housing

The included slot nuts can be easily inserted into the grooves of the sensor housing. The slot nuts have a metric M6 thread.

Each sensor with a measurement range of 20 m or lower is delivered with two slot nuts. Each sensor with a measurement range of 25 m or greater is delivered with four slot nuts.

# 5.5. 900



#### 2. by angle clamp brackets

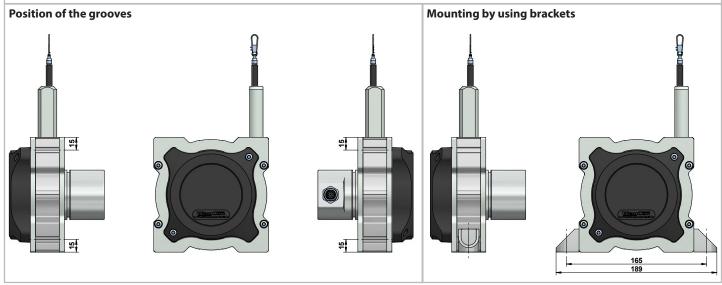
The angle clamp brackets feature a bore for M6 screws to fix it on a plate / slab or a profile.

Each sensor with a measurement range of 20 m or lower is delivered with two brackets. Each sensor with a measurement range of 25 m or greater is delivered with four brackets.



#### Note:

The grooves of the sensor housing, the slot nuts and brackets are compatible to the aluminium building kit system from *item Industrietechnik GmbH*.



The following table gives an overview of frequently used options, with which the standard sensors can be equipped. Please pay attention that not all options can be combined. Information on possible combinations can be found in the order codes.

| Option  | Order code | Descript  | ion  |
|---|------------|---|--|
| Changed cable or connector orientation (NOT with analog output) | K1, K2, K3 | Rope outlet points upwards: Standard: sideways, opposite to the rope outlet K1: at the top K2: sideways, same side as the rope outlet K3: at the bottom                       | Option K2  Option K2  Standard for cable / connector  Option K3                        |
| Improved linearity  | L02        | Improved linearity 0.02 %   |  |
| Inverted output signal<br>(analog output only)                  | IN         | The analog signal of the sensor is increasing by extracting the rope (standard). Option IN inverts the signal, i.e. the signal of the sensor declines by extracting the rope. | inverted inverted standard range extracted extracted range                             |
| Synthetic wire rope (instead of stainless steel wire rope)      | COR        | Synthetic wire rope, made out of abrasion resistant a   | nd enhanced Coramid.   |
| Rope fixation by M4 thread                                      | M4         | Optional, pivoted rope fixation with screw thread M4, length 22 mm. Ideal for attachment to through holes or thread holes M4.   | rope clip with drill protection (standard)  optional M4 rope fixation                  |
| Rope fixation by eyelet   | RI         | The end of the wire rope is equipped with a eyelet instead of a rope clip. Inside diameter 20 mm  |  |
| Protection class IP67   | IP67       | Use option IP67, if the sensor will operate in a humic may occur a light hysteresis in the output signal due displacement speed are reduced to 80 % of the spec               | to the special sealing. The max. acceleration and                                      |
| Corrosion protection  | СР         | Includes a V4A wire rope, stainless steel bearings HARTCOAT® coated. This coating is a hard-anodic ox by aggressive media (e. g. sea water) with a hard cera                  | idation that protects the sensor from corrosion  |
| Increased corrosion protection (analog output only)             | ICP        | Components of the housing and the rope drum get I Includes the options CP, IP67 and M4.   | HARTCOAT® coated.  |
| Increased temperature range High (potentiometer 1R only)        | T120       | Sensors with potentiometer output (1R) and cable outhis option is used. (NOT in combination with voltage  | utput can be operated from -20 to +120 °C when e-, current- or digital output signals) |
| Increased temperature range Low (analog output only)            | T40        | Special components and a low temperature grease n to +85 °C) possible.  | nake a working temperature down to -40 °C (up  |

Draw wire sensors with the analogue output versions 5VT and 10VT are equipped with teachable, internal electronics, called VT-Electronics. The signals provided by the sensor's potentiometer are digitized by the VT-Electronics. This digital information is first processed by the electronics, then transformed back and given out as an analogue output signal 0 to 5 V or 0 to 10 V.

The digitization offers two possibilities of adjustment, by which the sensor can be configured individually using the Squeezer:

- 1. Teaching of the measurement range. After a successful teaching process, the squeezer can be pulled off the sensor and be replaced by a standard cable or connector.
- 2. Setting an individual switching point. The squeezer allows the setting of an individual switching point open collector. The switching signal is emitted through the multi-functional line MFL.



A detailed description of the functions can be found in a separate manual.

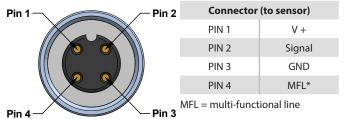
#### **Electrical connection Squeezer**

Accessory:

Connection cable sensor to

Squeezer:

K4P1,5M-SB-M12



| Cable ends (to PLC) |        |  |
|---------------------|--------|--|
| BN                  | V +    |  |
| WH                  | Signal |  |
| BU                  | GND    |  |
| BK                  | NPN*   |  |

\* The open collector is a NPN switching output

#### **GENERAL ACCESSORIES**

#### **Deflection pulley - UR2**

The rope must be extracted from the sensor vertically. The maximum variation from the vertical is 3°. A deflection pulley allows a change in the direction of the wire rope. Several pulleys may be used. The rope clip must not be guided over the deflection pulley.

Material foot:

anodised aluminium

Material rope wheel:

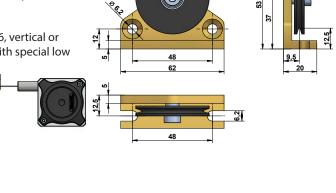
POM-C Mounting:

by 2 hexagon socket or countersunk screws M6, vertical or

horizontal mounting possible. Ball bearings: with special low

temperature grease and RS-sealing.





#### Rope extension - SV

For bridging a greater distance between the measuring target and the sensor a rope extension can be applied. The rope clip must not be guided over the deflection pulley.

Please specify the length needed in your order (XXXX). The minimum length is 150 mm:

SV1-XXXX: rope extension (150...4995 mm)

SV2-XXXX: rope extension (5000...19995 mm)

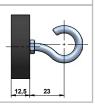
SV3-XXXX: rope extension (20000...40000 mm)

# Länge/ length [mm]

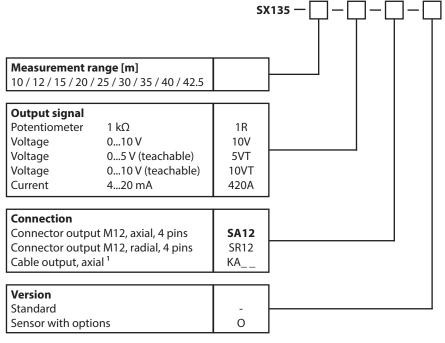
#### Magnetic clamp - MGG1

Use the magnetic clamp to quickly attach the rope to metallic objects without any assembly time. A rubber coating provides gentle contact (e.g., on varnished surfaces) and prevents from slipping due to vibration. The magnet consists of a neodym core for an increased adhesive force of 260 N. The hook makes it easy to attach the rope clip.





# **ORDER CODE ANALOG OUTPUT**

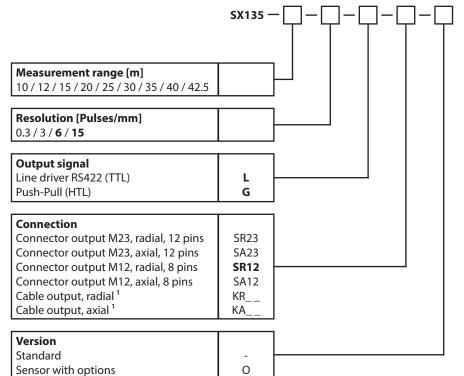


| Option | Description                     |
|--------|---------------------------------|
| IN     | inverted output signal          |
| M4     | rope fixation M4 thread         |
| RI     | rope fixation eyelet            |
| IP67   | protection class IP67           |
| CP     | corrosion protection            |
| ICP    | increased corrosion protection  |
| T40    | increased temperature -40+85 °C |

| Option | not combinable with |
|--------|---------------------|
| M4     | CP, ICP             |
| RI     | CP, ICP             |
| IP67   | T120, ICP           |
| CP     | M4, RI,             |
| ICP    | M4, RI, IP67        |

Examples: **KA02** = 2 m, KA05 = 5 m **Bold text:** standard with shorter lead time

# ORDER CODE DIGITAL OUTPUT INCREMENTAL



| Option | Description                        |
|--------|------------------------------------|
| K1     | cable/connector orientation top    |
| K2     | cable/connector orientation left   |
| K3     | cable/connector orientation bottom |
| L02    | improved linearity ±0.02 %         |
| M4     | rope fixation M4 thread            |
| RI     | rope fixation eyelet               |
| IP67   | protection class IP67              |
| СР     | corrosion protection               |
|        |                                    |

| Option | not combinable with |
|--------|---------------------|
| L02    | resolution 0.3/3    |
| M4     | CP                  |
| RI     | СР                  |
| CP     | M4, RI              |

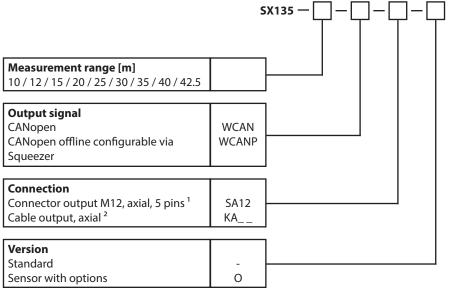
<sup>1</sup> Length in m (min. 2 m)

Examples: KR02 = 2 m, KR05 = 5 m

**Bold text:** standard with shorter lead time

<sup>&</sup>lt;sup>1</sup>Length in m (min. 2 m)

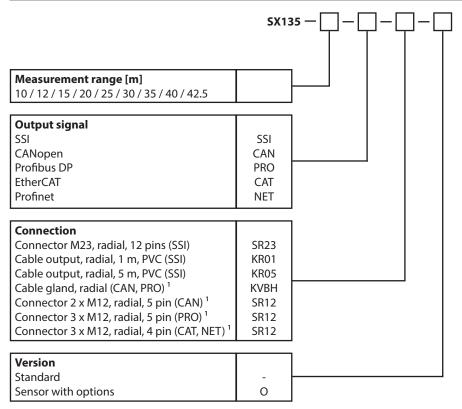
# **ORDER CODE DIGITAL OUTPUT ABSOLUTE CANopen (WCAN)**



| Option | Description                     |
|--------|---------------------------------|
| M4     | rope fixation M4 thread         |
| RI     | rope fixation eyelet            |
| IP67   | protection class IP67           |
| CP     | corrosion protection            |
| ICP    | increased corrosion protection  |
| T40    | increased temperature -40+85 °C |

| Option | not combinable with |
|--------|---------------------|
| M4     | CP, ICP             |
| RI     | CP, ICP             |
| IP67   | ICP                 |
| CP     | M4, RI              |
| ICP    | M4, RI, IP67        |

#### **ORDER CODE DIGITAL OUTPUT ABSOLUTE**



| Option | Description                        |
|--------|------------------------------------|
| K1     | cable/connector orientation top    |
| K2     | cable/connector orientation left   |
| K3     | cable/connector orientation bottom |
| M4     | rope fixation M4 thread            |
| RI     | rope fixation eyelet               |
| IP67   | protection class IP67              |
| CP     | corrosion protection               |

| Option | not combinable with |
|--------|---------------------|
| M4     | CP                  |
| RI     | CP                  |
| CP     | M4, RI              |

<sup>&</sup>lt;sup>1</sup>8 pins in combination with WCANP

<sup>&</sup>lt;sup>2</sup> Length in m (Minimum 2 m) Examples: KA02 = 2 m, KA05 = 5 m

<sup>&</sup>lt;sup>1</sup> removable bus terminal cover

| MGG1     | magnetic clamp                           |
|----------|--|
| SV1-XXXX | rope extension (150 mm up to 4995 mm)    |
| SV2-XXXX | rope extension (5000 mm up to 19995 mm)  |
| SV3-XXXX | rope extension (20000 mm up to 40000 mm) |

# **ACCESSORIES ANALOG OUTPUT**

| Cable with mating connector M12, 4 poles, shielded |                          |  |
|--|--------------------------|--|
| K4P2M-S-M12  | 2 m, straight connector  |  |
| K4P5M-S-M12  | 5 m, straight connector  |  |
| K4P10M-S-M12                                       | 10 m, straight connector |  |
| K4P2M-SW-M12                                       | 2 m, angular connector   |  |
| K4P5M-SW-M12                                       | 5 m, angular connector   |  |
| K4P10M-SW-M12                                      | 10 m, angular connector  |  |

| Mating connector M12, 4 poles, shielded |                                 |
|---|---------------------------------|
| D4-G-M12-S                              | straight, M12 for self assembly |
| D4-W-M12-S                              | angular, M12 for self assembly  |
|   |                                 |
| Connection cable sensor to Squeezer     |                                 |
| K4P1,5M-SB-M12                          | 1.5 m, 4-pole, shielded         |

# **ACCESSORIES DIGITAL OUTPUT INCREMENTAL**

| Cable with mating connector M12, 8 poles, shielded |                          |  |
|--|--------------------------|--|
| K8P2M-S-M12  | 2 m, straight connector  |  |
| K8P5M-S-M12  | 5 m, straight connector  |  |
| K8P10M-S-M12                                       | 10 m, straight connector |  |
| K8P2M-SW-M12                                       | 2 m, angular connector   |  |
| K8P5M-SW-M12                                       | 5 m, angular connector   |  |
| K8P10M-SW-M12                                      | 10 m, angular connector  |  |
|  |                          |  |

| Cable with mating                        | Cable with mating connector M23, 12 poles, shielded |  |  |
|--|---|--|--|
| K8P2M-S-M23                              | 2 m, straight connector                             |  |  |
| K8P5M-S-M23                              | 5 m, straight connector                             |  |  |
| K8P10M-S-M23                             | 10 m, straight connector                            |  |  |
|  |   |  |  |
| Mating connector M23, 12 poles, shielded |   |  |  |
| CON012-S                                 | straight, M23 for self assembly, metal housing      |  |  |
|  |   |  |  |

| Mating connector M12, 8 poles, shielded |                                 |
|---|---------------------------------|
| D8-G-M12-S                              | straight, M12 for self assembly |
| D8-W-M12-S                              | angular, M12 for self assembly  |

# ACCESSORIES DIGITAL OUTPUT ABSOLUTE CANopen (WCAN)

| Cable with mating connector M12, 5 poles, shielded |                         |  |
|--|-------------------------|--|
| K5P2M-S-M12  | 2 m, straight connector |  |
| K5P2M-SW-M12                                       | 2 m, angular connector  |  |

| Connection cable sensor to Squeezer for WCANP |                                     |  |
|---|-------------------------------------|--|
| K48P03M-SB-M12                                | 0.3 m, shielded, 8 poles to 4 poles |  |
|   |                                     |  |

| Cable for WCANP with mating connector M12, 8 poles, shielded |                         |
|--|-------------------------|
| K8P2M-S-M12  | 2 m, straight connector |
| K8P2M-SW-M12   | 2 m, angular connector  |
|  |                         |

| Adapter cable WCANP to CAN-Bus |                                     |  |
|--------------------------------|-------------------------------------|--|
| K58P03M-SB-M12                 | 0.3 m, shielded, 8 poles to 5 poles |  |
|                                |                                     |  |

# **ACCESSORIES DIGITAL OUTPUT ABSOLUTE SSI**

| Cable with mating connector M23, 12 poles, shielded |                          |  |
|---|--------------------------|--|
| K12P02M-S-M23-SSI                                   | 2 m, straight connector  |  |
| K12P05M-S-M23-SSI                                   | 5 m, straight connector  |  |
| K12P10M-S-M23-SSI                                   | 10 m, straight connector |  |
| K12P15M-S-M23-SSI                                   | 15 m, straight connector |  |
|   |                          |  |

| Mating connector M23, 12 poles, shielded |  |
|--|--|
| CON012-S                                 | straight, M23 for self assembly, metal housing |
|  |  |
|  |  |
|  |  |

#### Cable with mating connector M12, 5 poles, shielded

K5P2M-B-M12-CAN 2 m, plug female M12, open ends

K5P2M-SB-M12-CAN 2 m, connector male M12, plug female M12 K5P2M-S-M12-CAN 2 m, connector male M12, open ends

#### **ACCESSORIES DIGITAL OUTPUT ABSOLUTE PROFIBUS**

#### Cable with mating connector M12, 5 poles, shielded

K5P2M-B-M12-PROF 2 m, plug female M12, open ends

K5P2M-SB-M12-PROF  $\,\,$  2 m, connector male M12, plug female M12

K5P2M-S-M12-PROF 2 m, connector male M12, open ends

#### Other

M12-PROF-AW termination resistor

# **ACCESSORIES DIGITAL OUTPUT ABSOLUTE EtherCAT AND PROFINET**

#### Cable with mating connector M12, 4 poles, shielded

K4P2M-S-M12-CAT 2 m, connector male M12, open ends K4P5M-S-M12-CAT 5 m, connector male M12, open ends

K4P10M-S-M12-CAT 10 m, connector male M12, open ends

#### Cable with mating connector M12, 4 poles, shielded

K4P2M-SS-M12-CAT 2 m, plug female M12, open ends
 K4P5M-SS-M12-CAT 5 m, plug female M12, open ends
 K4P10M-SS-M12-CAT 10 m, plug female M12, open ends

Please note, that an additional cable is required for the power supply. Appropriate cables can be chosen from the list of the "Accessories Analog Output".